



2025年人工智能学院导师交流

赵鹏

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2025.10.11

关于我

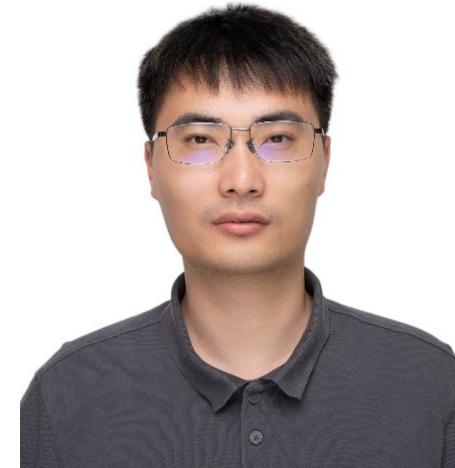
赵鹏，博士，副教授

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主页：<https://www.pengzhao-ml.com/>

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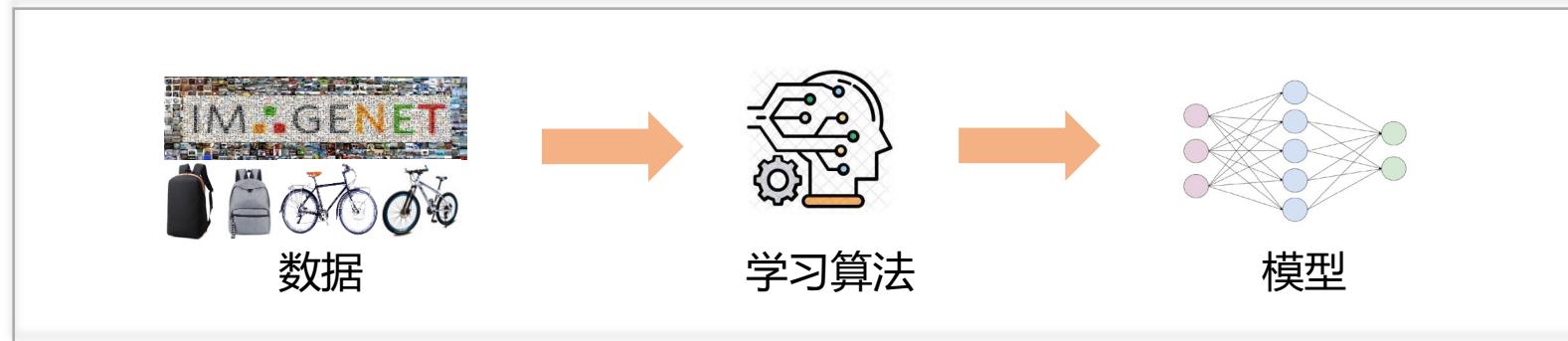


研究方向

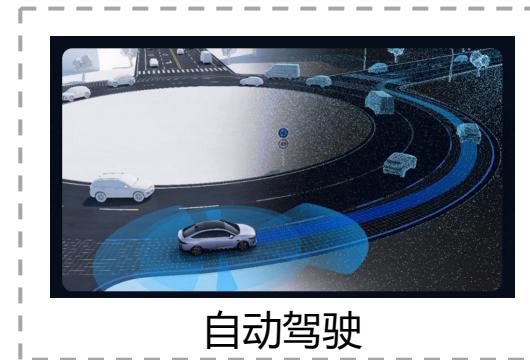
- 开放环境机器学习
- 在线学习、强化学习
- 大模型优化等相关应用

研究方向

- 机器学习是这一轮人工智能热潮的核心推动技术



- 越来越多应用中，环境呈现“开放动态”，数据呈现“流式积聚”



自动驾驶



智能制造



基站通讯

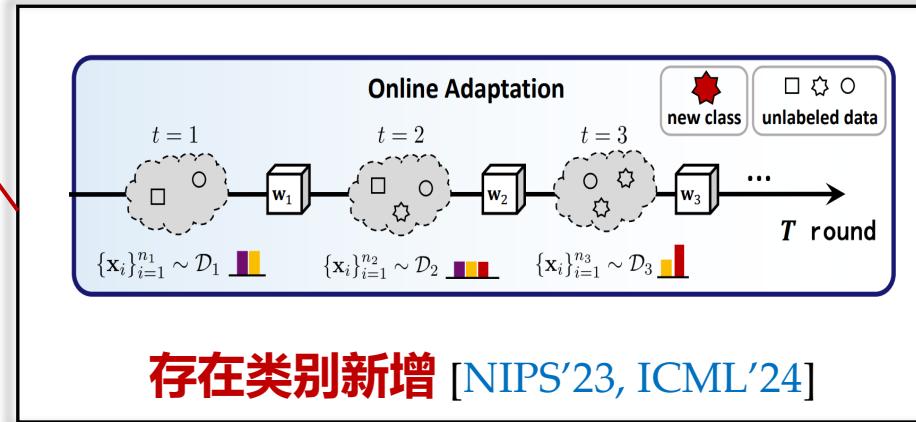
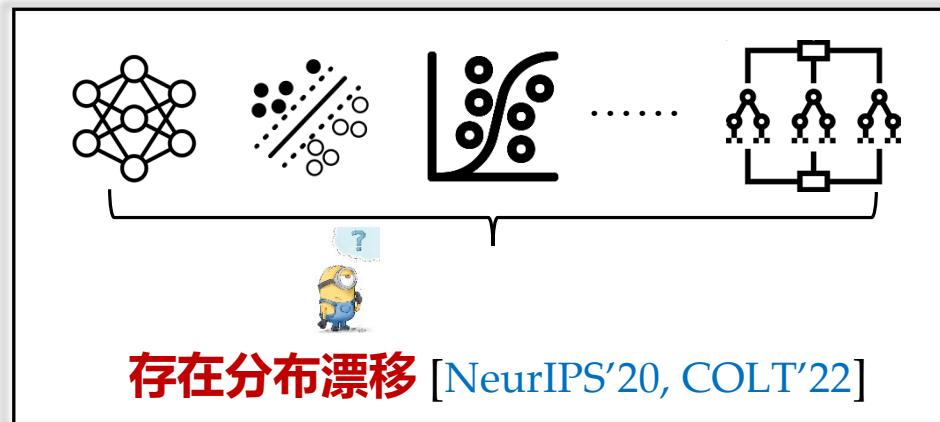
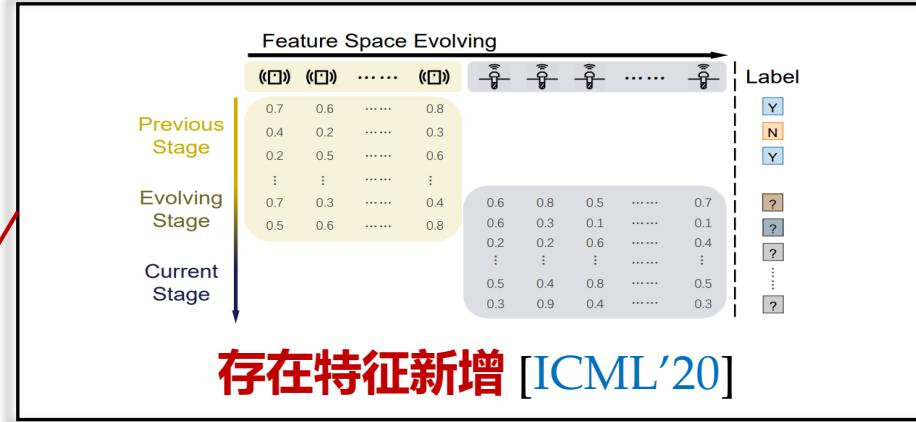
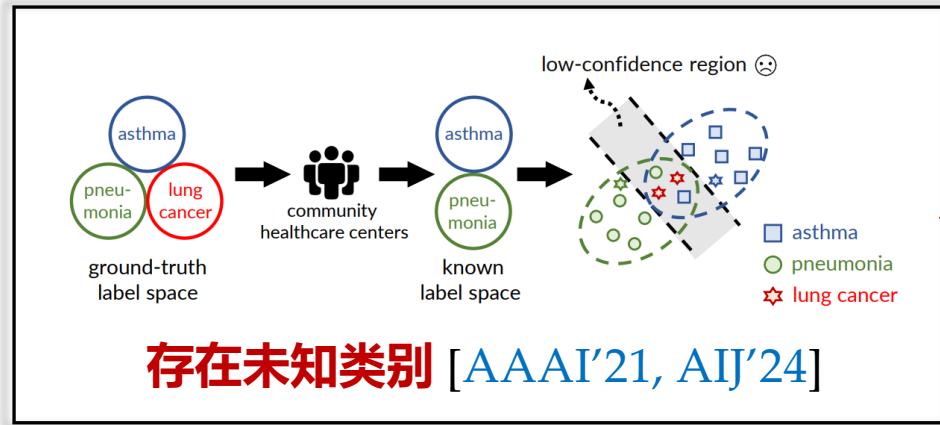
研究方向

- 探究机器学习与大模型基础理论，指导算法设计，赋能实际应用

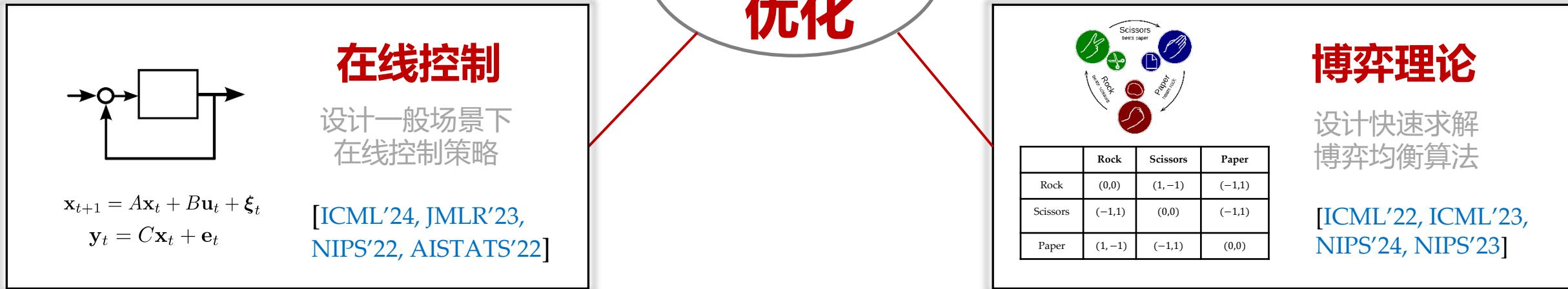
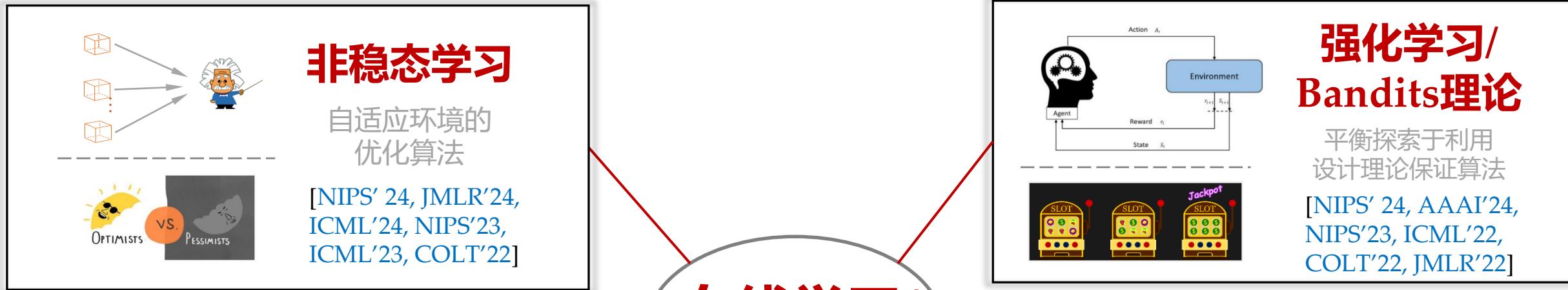
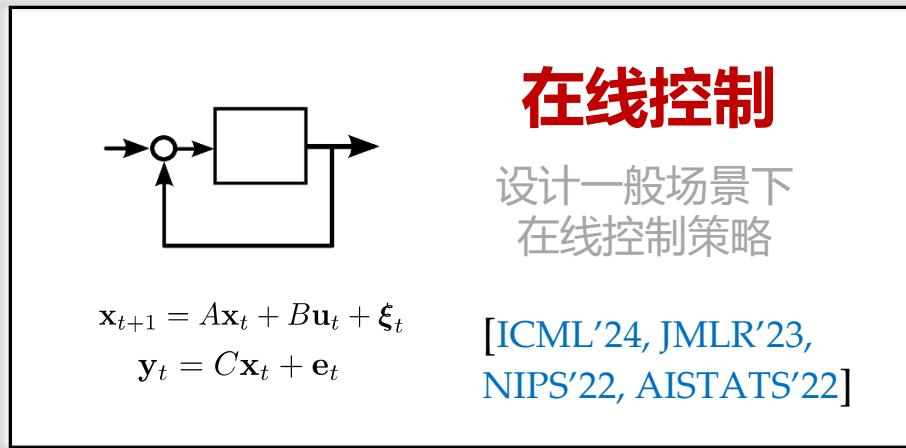
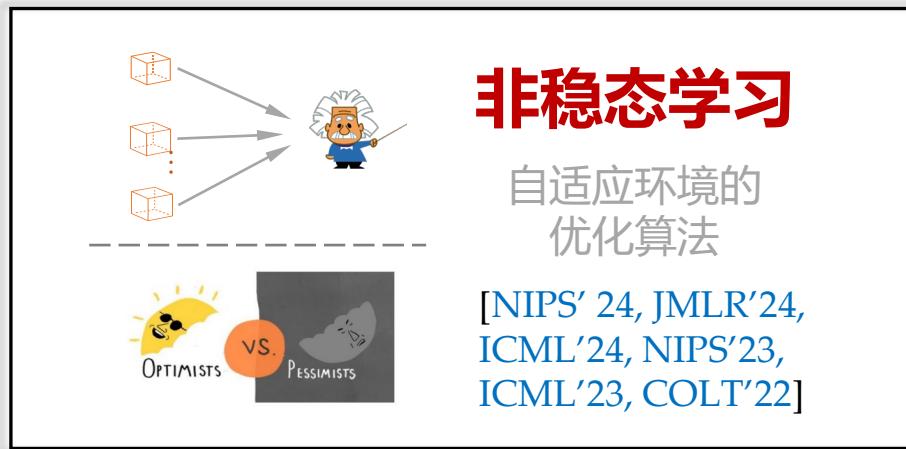
机器学习与优化：理论与应用



一、开放环境机器学习理论



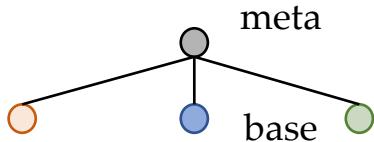
二、在线学习及优化



二、在线学习及优化

在线优化理论

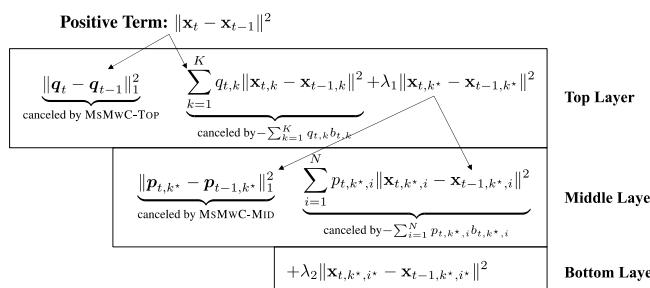
通过集成处理环境中不确定性



自适应：合理利用环境信息

$$\sum_{t=1}^T (r_{t,i^*} - m_{t,i^*})^2 \leq \begin{cases} \sum_{t=1}^T \langle \nabla f_t(\mathbf{x}_t), \mathbf{x}_t - \mathbf{x}_{t,i^*} \rangle^2, & (\text{exp-concave \& strongly convex}) \\ V_T + \sum_{t=2}^T \|\mathbf{x}_{t,i^*} - \mathbf{x}_{t-1,i^*}\|^2 + \sum_{t=2}^T \|\mathbf{x}_t - \mathbf{x}_{t-1}\|^2. & (\text{convex}) \end{cases}$$

最优性：确保集成误差可控



在线博弈理论

在复杂环境下求解博弈均衡策略

$$\text{Dynamic NE-regret: } \left| \sum_{t=1}^T \mathbf{x}_t^\top \mathbf{A}_t \mathbf{y}_t - \sum_{t=1}^T \mathbf{x}_t^* \top \mathbf{A}_t \mathbf{y}_t^* \right|$$

利用算法稳定性进行快速求解

$$\sum_{t=1}^T \langle \mathbf{A}_t \mathbf{y}_t, \mathbf{x}_{t,i} - \mathbf{u}_t^x \rangle \lesssim \frac{1+P_T^x}{\eta_i^x} + \eta_i^x \sum_{t=2}^T \|\mathbf{A}_t \mathbf{y}_t - \mathbf{A}_t \mathbf{y}_{t-1}\|^2 - \frac{1}{\eta_i^x} \sum_{t=2}^T \|\mathbf{x}_{t,i} - \mathbf{x}_{t-1,i}\|^2$$

$$\sum_{t=1}^T \langle -\mathbf{A}_t \mathbf{x}_t, \mathbf{y}_{t,j} - \mathbf{u}_t^y \rangle \lesssim \frac{1+P_T^y}{\eta_j^y} + \eta_j^y \sum_{t=2}^T \|\mathbf{A}_t \mathbf{x}_t - \mathbf{A}_t \mathbf{x}_{t-1}\|^2 - \frac{1}{\eta_j^y} \sum_{t=2}^T \|\mathbf{y}_{t,j} - \mathbf{y}_{t-1,j}\|^2$$

添加修正项处理算法复杂结构

$$\sum_{t=2}^T \|\mathbf{x}_t - \mathbf{x}_{t-1}\|^2 \lesssim \|\mathbf{p}_t - \mathbf{p}_{t-1}\|_1^2 + \boxed{\sum_{i=1}^N p_{t,i} \|\mathbf{x}_{t,i} - \mathbf{x}_{t-1,i}\|^2}$$

$$\sum_{t=1}^T \langle \ell_t, \mathbf{p}_t - \mathbf{e}_{i^*} \rangle \leq R_T - \sum_{t=1}^T \sum_{i=1}^N p_{t,i} b_{t,i} + \sum_{t=1}^T b_{t,i^*}$$

相消

强化学习理论

考虑非稳态下 linear mixture MDP

$$\mathbb{P}_h(s' | s, a) = \phi(s'|s, a)^\top \theta_h^*, \quad \forall (s, a, s')$$

occupancy-based 方法更新策略

$$\hat{q}_{k+1,i} = \arg \max_{q \in \Delta(\mathcal{P}_k, \alpha)} \eta_i \langle q, r_k \rangle - D_\psi(q, \hat{q}_{k,i})$$

$$p_{k+1,i} \propto \exp \left(\varepsilon \sum_{j=1}^k h_{j,i} \right) \text{ with } h_{k,i} = \langle \hat{q}_{k,i}, r_k \rangle$$

policy-based 方法评估策略

$$\hat{\theta}_{k,h} = \arg \min_{\theta \in \mathbb{R}^d} \sum_{j=1}^{k-1} [\langle \phi_{V_{j,h+1}}(x_{j,h}, a_{j,h}), \theta \rangle - V_{j,h+1}(x_{j,h+1})]^2 / \sigma_{j,h}^2 + \lambda \|\theta\|^2$$

$$Q_{k,h}(\cdot, \cdot) = \left[r_{k,h}(\cdot, \cdot) + \min_{\theta \in \mathcal{C}_{k,h}} \langle \theta, \phi_{V_{k,h+1}}(\cdot, \cdot) \rangle \right]_{[0,H]}$$

巧妙结合二者优点，取得最优保障

$$\text{D-Reg}_K \leq \tilde{\mathcal{O}} \left(\sqrt{d^2 H^3 K} + \sqrt{HK(H + \bar{P}_K)} \right).$$

三、大模型高效推理优化加速等

Online RLHF Pipeline: A Pytorch Implementation

A PyTorch implementation of the paper "Provably Efficient RLHF Pipeline: A Unified View from Contextual Bandits". This repository provides a flexible and modular approach to Reinforcement Learning from Human Feedback (RLHF). This repository is forked from [OpenRLHF](#) repo, and modified to implement our Online RLHF Pipeline.

Cook Your Own Online-RLHF Recipe!

Think of Online-RLHF training as cooking - each step is an ingredient that contributes to the final dish. This implementation lets you mix and match different training components to create your perfect RLHF recipe!

Recipe Format

- # A recipe is a list of ingredients (steps):
- # 1. Single ingredient: A string representing one step (e.g., "SFT")
- # 2. Ingredient group: A list of steps that cook together in one iteration

大语言模型RLHF对齐 [NeurIPS'25]

PyNOL

PyNOL is a Python package for Non-stationary Online Learning.

The purpose of this package is to provide a general framework to implement various algorithms designed for online learning in non-stationary environments. In particular, we pay special attention to those online algorithms that provably optimize the *dynamic regret* or *adaptive regret*, two widely used performance metrics for non-stationary online learning.

There are various algorithms devised to optimize the measures (*dynamic regret* or *adaptive regret*) during the decades, see [2, 9, 12, 21, 23, 24, 25, 27] for dynamic regret and [7, 11, 13, 20, 22] for adaptive regret. By providing a unified view to understand many algorithms proposed in the literature, we argue that there are three critical algorithmic components: base-learner, meta-learner, and schedule. With such a perspective, we present systematic and modular Python implementations for many online algorithms, packed in PyNOL. The package is highly flexible and extensible, based on which one can define and implement her own algorithms flexibly and conveniently. For example, we also implement some classical algorithms for online MDPs based on this package [4, 18, 24, 29].

非稳态在线学习工具包PyNOL

Step 1: Generate high-confidence pseudo-labeled data

Black-box LLM → unlabeled dataset → x_{hc}

Step 2: Construct prompt and in-context demonstrations

Black-box LLM → unlabeled dataset → x_{demo}

Step 3: Update category distribution by policy gradient descent

Black-box LLM → unlabeled dataset → x_{hc} → \hat{y}

大模型快速微调及推理加速 [ICML'25]

通讯基站调优、口腔医院等应用

在线学习：交互式范式

- Agent能力的突破，越来越多面临“开放动态”挑战
- 在线学习是大模型下一轮能力的重要推动力

深度讨论 Online Learning : 99 条思考读懂 LLM 下一个核心范式
| Best Ideas

原创 Best Ideas 社群 海外独角兽 2025年09月30日 20:04 日本



Best Ideas 深度讨论
Together, We Think Differently

Online Learning

Live Highlights

- Online learning 是 LLM 下一个核心范式
- Online learning 和 Online RL 不一样
- 极致个性化只是低阶目标，最终目标是提升 AI 系统智能
- Reward 信号获取很关键
- Online Learning 是一种新的交互和推理范式
- 数据分布差异越大，Online learning 价值越突出

研究成果及国际影响

- 在机器学习顶级学术期刊论文发文70余篇，包括

- 期刊：JMLR 6 篇、AIJ 1 篇、IEEE TKDE 4 篇等

- 会议：COLT 2 篇、NeurIPS 18 篇、ICML 11 篇、AITSTATS 7 篇等

研究成果得到包括麻省理工、哈佛、斯坦福等**国际著名单位研究组**关注



研究成果得到**国际知名学者、领域同行**引用，并使用“follow, build on, inspired by, extend, insightful work, optimal, simplicity”等正面评价



Shankar Sastry

IEEE/IFAC Fellow
美国国家工程院院士
美国艺术与科学学院院士
美国加州大学伯克利分校教授



Elad Hazan

国际计算学习理论顶会
COLT 2015程序主席
在线凸优化领域权威
美国普林斯顿大学教授



David Woodruff

国际理论计算机科学顶会
SODA 2024程序主席
国际数据挖掘顶会KDD 2014最佳论文获得者
美国卡耐基梅隆大学教授



John Lygeros

国际控制领域著名会议
HSCC 2014程序主席
国际控制域著名会议
ECC 2013程序主席
苏黎世联邦理工大学教授



Kilian Q. Weinberger

AAAI 2011程序主席
ICML 2016程序主席
ICML 2023 PC
康奈尔大学教授

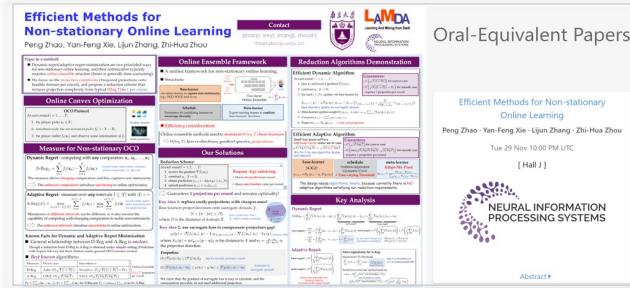


Tuomas Sandholm

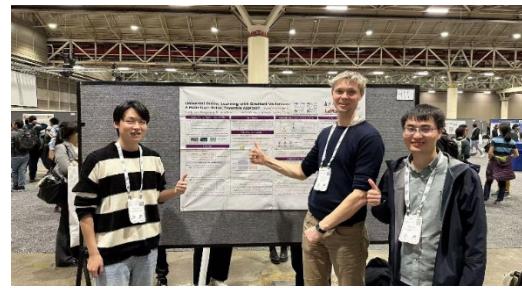
ACM/AAAI/AAAS Fellow
德州扑克AI之父
IJCAI Minsky Medal,
IJCAI McCarthy Award得主
卡耐基梅隆大学教授

研究成果及国际影响

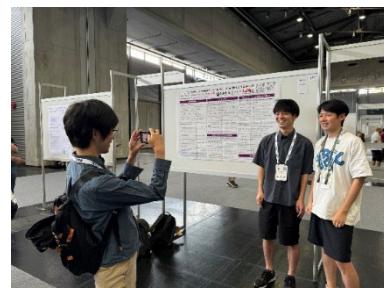
- 研究工作连续四年入选机器学习顶会ICML/NeurIPS的Oral/Spotlight展示



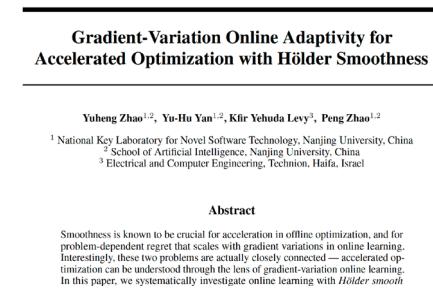
NeurIPS'22 Oral
(录用率1.76%)



NeurIPS'23 Spotlight (录用率3.6%)

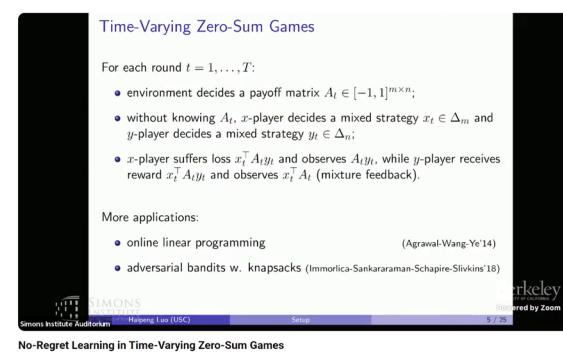
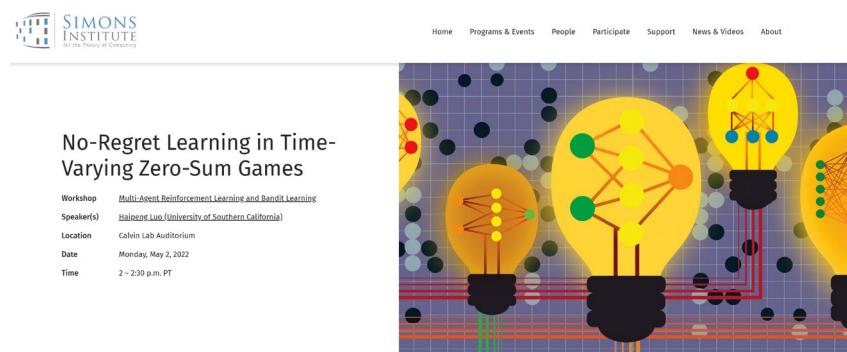


ICML'24 Spotlight
(录用率3.5%)

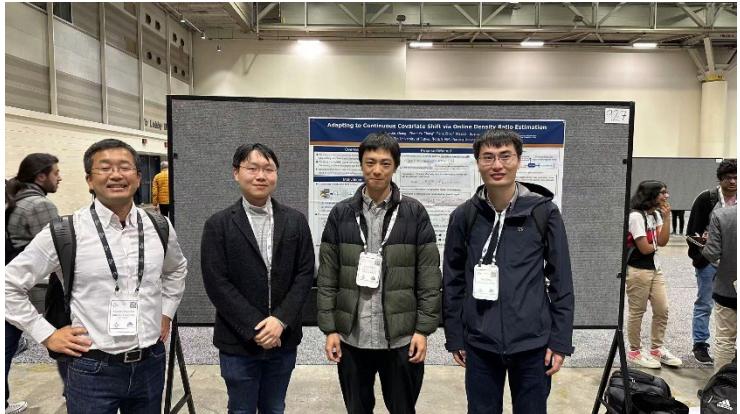


NeurIPS'25 Spotlight (录用率3.5%)

- 研究工作受邀到理论计算机科学领域著名的Simons Institute报告



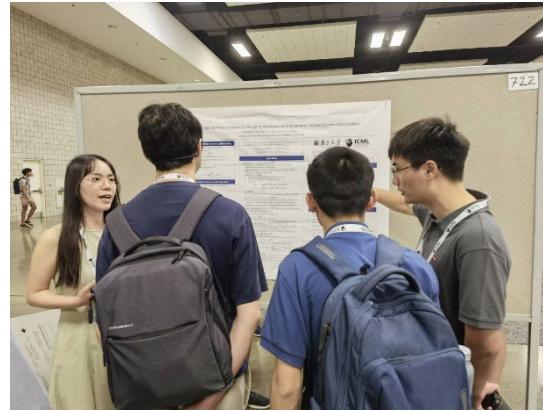
国际报告及交流



NeurIPS'23



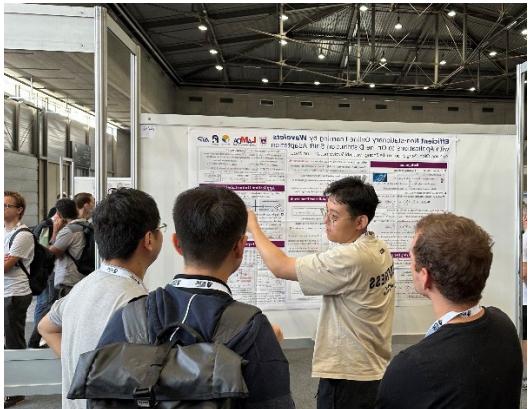
UCSB学术报告



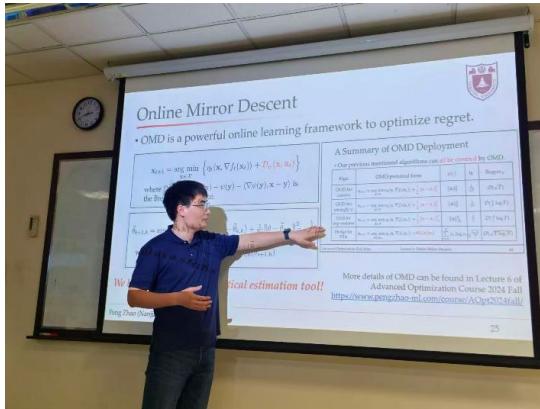
ICML'23



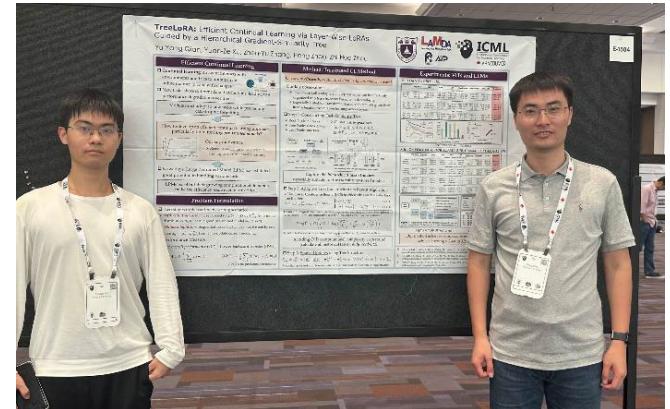
ICML'24



ICML'24



ICLR'25 & NUS visit



ICML'25

国际学术交流

- 邀请国内外同行前来南大进行报告



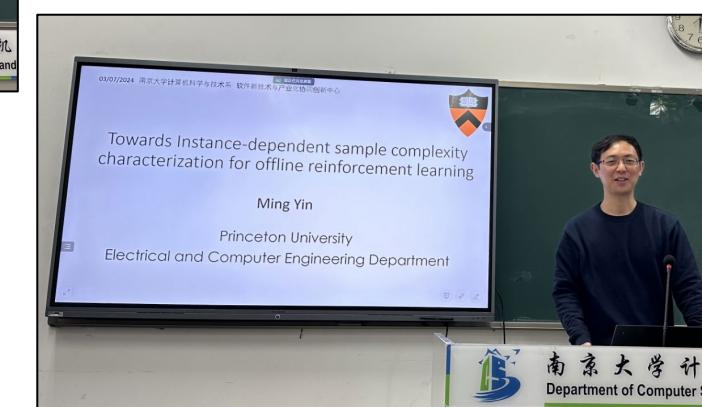
清华特奖得主
MIT博士生 戴言



Harvard Postdoc
马里兰大学助理教授 邵涵



Yale Ph.D.
Weiqiang Zheng

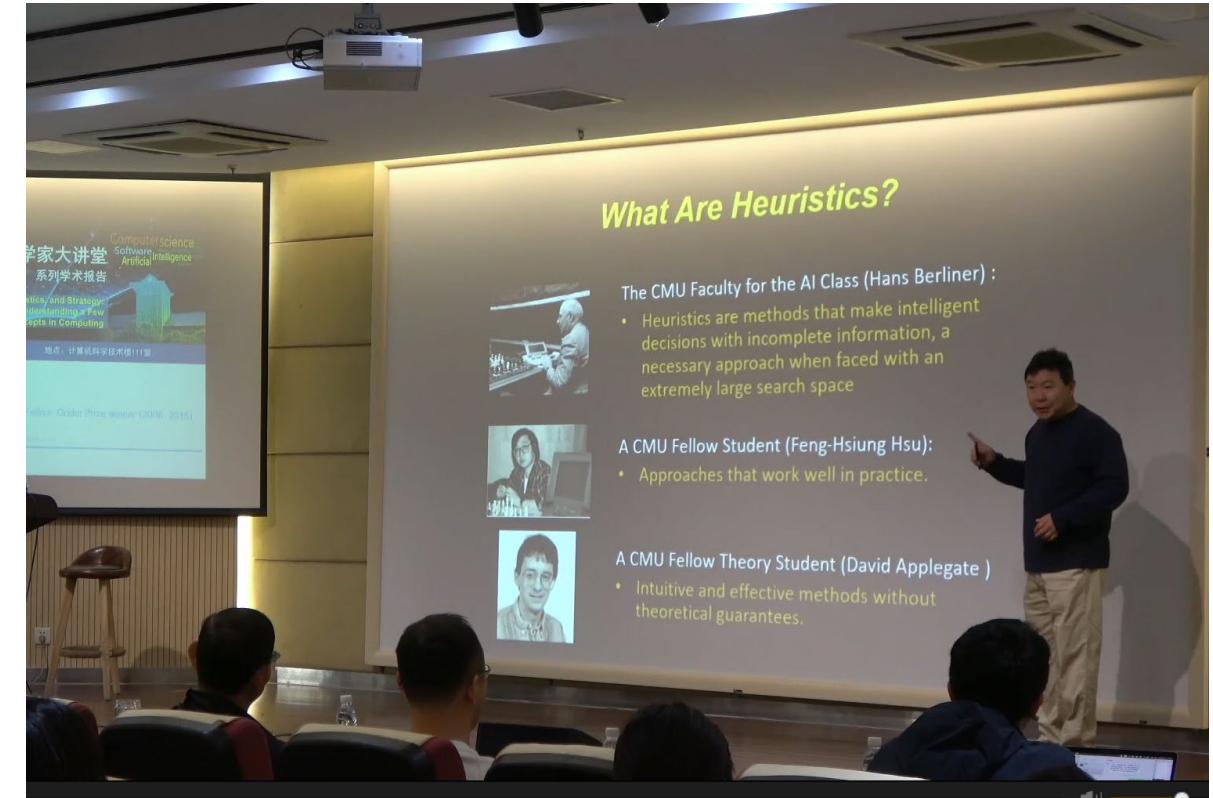


Princeton Postdoc
Ming Yin

Prof. Shang-Hua Teng @ USC

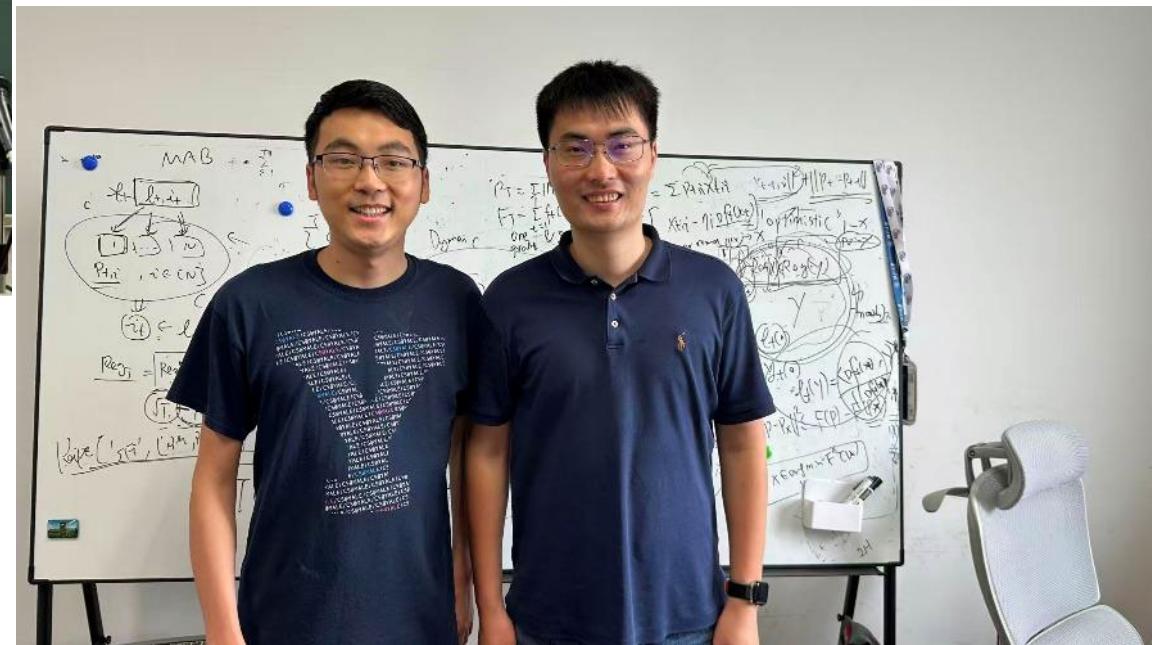


2025.04.18 - 04.20



Dr. Weiqiang Zheng @ Yale

2025.05.23 - 05.29



Prof. Yu-Xiang Wang @ UCSD

2025.06.30 - 07.04



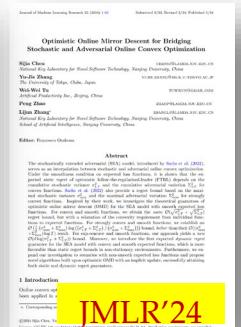
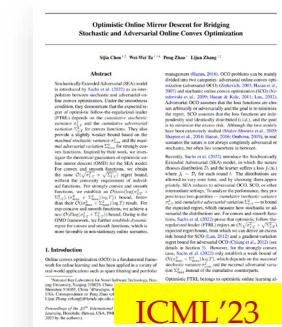
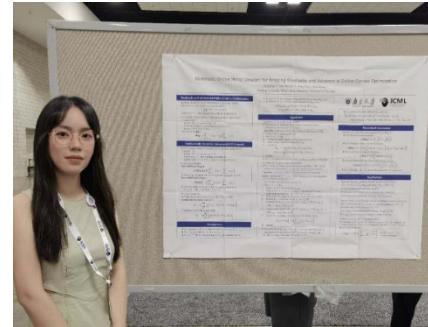
国际化合作丰富

- 美国、日本、以色列、新加坡，建立了充分的国际学术交流合作



本科生培养

- 指导本科生陈思佳同学，研究工作发表于**机器学习顶会ICML'23**，
期刊拓展版发表于**顶刊JMLR'24**



- 组内本科生出国访问，推荐支持



国院大三学生李想，在**加州伯克利大学交换**
并参与Peter Bartlett教授科研组进行科研实习



人工智能学院大四学生郁航，在**匹兹堡大学及**
卡耐基梅隆大学进行科研实习并参与课程学习

组内定期团建活动



梅花山春游 (2023.03.02)



皖南秋游 (2023.10.15)



羽毛球乒乓球活动 (weekly)



奥本海默观影 (2023.09.14)



毕业真人cs对抗
(2025.06.20)

入组培养

- 研究方向
 - 理论方法：机器学习理论、在线学习/优化
 - 算法应用：大模型优化、强化学习、Agent
- 夯实理论基础
 - 周组会：接触前沿学习理论及优化研究
 - 读书班：机器学习理论、优化方面经典教材
- 工程实践项目
 - 大创/竞赛/实践项目；校企合作接触实际数据

精力有限：~1名理论，~3名算法应用

招生说明：https://www.pengzhao-ml.com/for_student.html



国际视野，尊重学术，氛围和谐

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组内研究生 郁航 (13706280491, 微信同号)

谢谢！